

The parameters are dependent on process parameters (feed, nose radius etc.). During the rotation of a turned shaft, the liquid entrains in the circumferential direction and is deflected axially because of the twist structures [5].

The industry is currently looking for alternative manufacturing processes, for example hard turning, milling, burnishing or laser polishing. Besides these processes there are two similar technologies, the Magnetic Abrasive Polishing (MAP) and the Magnetic Assisted Roller Burnishing (MARB) which are also able to produce twist-free surface.

III. MAM TECHNOLOGIES

Denomination Magnetism Aided Machining (MAM) comprises a number of relatively new industrial machining processes (mainly finishing and surface improving) developed presently, too.

The magnetic force makes these processes simpler and more productive. Machining force is generated by an adjustable electromagnetic field between two magnetic poles within the working area ensuring the necessary pressure and speed difference between the tools (abrasive grains, pellets or rollers) and the workpiece [6].

A. Magnetic Abrasive Polishing (MAP)

The polishing for decrease of surface roughness and increase of resistance against wear, corrosion and produce twist-free surface. Magnetic Abrasive Polishing is one such unconventional finishing process developed recently to produce efficiently and economically good quality finish. In this process, usually use ferromagnetic particles are sintered with fine abrasive particles (Al_2O_3 , SiC, CBN or diamond). The MAP equipment for cylindrical surfaces was adapted to a universal engine lathe (Fig. 2.) [7].

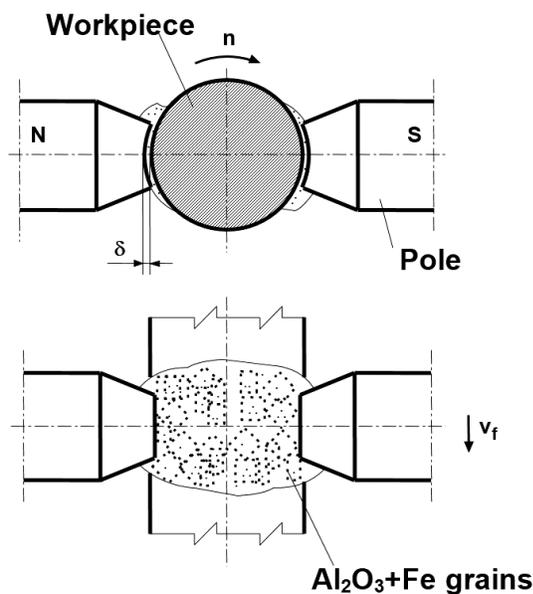


Fig. 2. MAP technology [7]

B. Magnetic Assisted Roller Burnishing (MARB)

The main goal of roller burnishing is to achieve high-quality smooth surfaces or surfaces with pre-defined surface

finish. During the process one or more balls plastically deform the surface layer of workpiece (Fig. 3.).

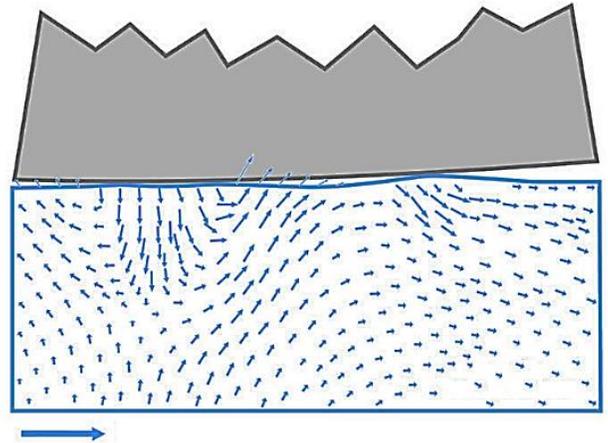


Fig. 3. Material flow [8]

In case, if this stress is higher than yield strength of the material, the material near the surface starts to flow. As the ball moves across the workpiece surface, the peaks of surface are pressed down, almost vertically, into the surface and the material then flows into the valleys between the peaks as you see in (Fig. 4.) [8].

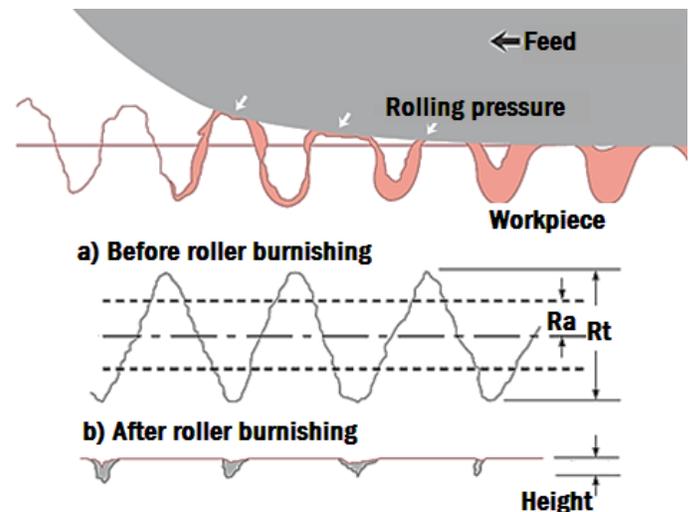


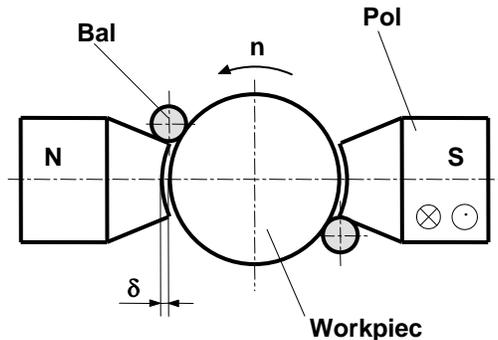
Fig. 4. Evolution of surface by roller burnishing [8]

Most of manufacturing processes which result high-quality surfaces can be replaced by roller burnishing (e.g. fine turning, grinding, superfinishing, lapgrinding). The roller burnishing technology able to reduce the surfaces roughness ($Rz < 10 \mu m$) and increase the hardness in micron depth [8].

For roller burnishing was applying mechanical force to press the rolling ball onto the surfaces. To avoid the harmful deformation by mechanical pressing the necessary pressure and relative speed between the tools and the workpiece are ensured by the magnetic force.

The burnishing operation was performed by hardened steel balls of 6...12 mm diameter ($HRC = 60$), with $v = 20...800$ m/min peripheral speed and $f = 0,05...0,3$ mm/rev feed. The balls were set above or under the jaws in radius-shaped slots preventing the balls from any kind of axial displacement. The

magnetic force kept the balls in the slots and – depending on the scale of magnetic induction – pressed them to the surface of the workpiece with a force of 50 ... 100 N. The balls could freely roll perpendicularly to the rotational axis of the workpiece following the eventual macro-unevenness of the cylindrical surface. The burnishing operation consisted of a double-stroke motion of the slide along the rotating workpiece, in feed direction.



The magnetic roller burnishing equipment for cylindrical surfaces was adapted to a universal engine lathe (Fig. 5.).

Fig. 5. MARB technology [7]

Important about this technology that the magnetizable steel could be burnished more effectively than the nonmagnetic Al-alloy, due to the higher magnetic force. In case, if the workpiece material nonmagnetic the magnetic force line not able to press the ball to the surface (Fig. 6).

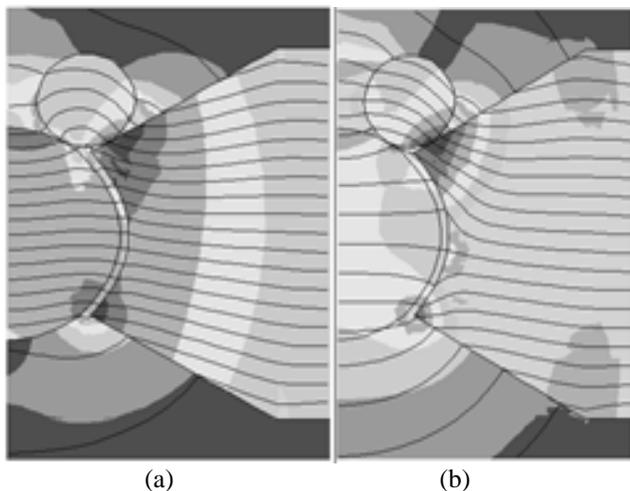


Fig. 6. Magnetic lines for steel a) and Al-alloy b) workpiece material [7]

For the modelling system, the magnetic force components were computed using the (2, 3, 4) equations [7].

$$F_x = V \cdot H \cdot \left(\frac{\partial H}{\partial x} \right) (\mu - \mu_0) \quad (1)$$

$$F_y = V \cdot H \cdot \left(\frac{\partial H}{\partial y} \right) (\mu - \mu_0) \quad (2)$$

$$F = (F_x^2 + F_y^2)^{\frac{1}{2}} \quad (3)$$

where F is the magnetic force (including the components too), V is the volume of the burnishing ball, H is the intensity of the magnetic field, μ and μ_0 are magnetic permeability of the ball material and the vacuum, respectively.

IV. EXPERIMENTAL SETUP

In the performed investigations the shaft surfaces were manufactured purposefully by turning using different cutting tool. Then the surface was machined MAM technologies (MARB and MAP), see in the Fig. 7.



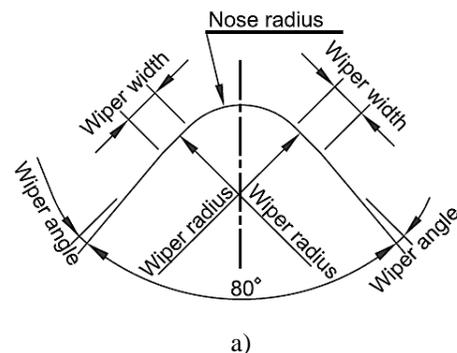
(a)



(b)

Fig. 7. Picture about the MA Polishing a) and Roller Burnishing b)

Furthermore was made a grinded part as a reference to be able to compare the surfaces made by different technologies. During processing the workpieces C45-type steel with a diameter of 26 mm and a length of 100 mm were selected as processing elements. Cutting tool was inserts with wiper geometry (WNMG080404W-MF2, TP2501) and conventional inserts (WNMG080404-MF2, TP2501) (Fig 8.).



a)

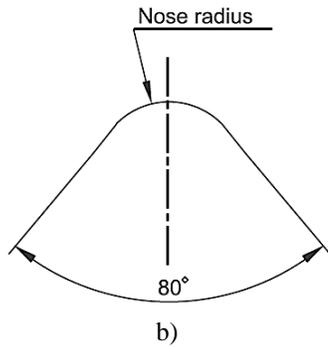


Fig. 8. Geometry of Wiper a) and conventional b) insert [4]

The MAM equipment is able to work as polishing and rolling function where the electromagnetic poles were fixed onto the slide of the lathe. In the tests the voltage ($U = 40$ V), current ($I = 10$ A) (direct current, adjustable) and the generating magnetic induction ($B = 0,96$ T) were the same under rolling and polishing too. The generated magnetic induction was reduced ($B = 0,75$ T) with polishing grain because of the applied Al_2O_3 shielding properties. The magnetic jaws (poles) surrounded the workpiece with a $\delta = 3$ mm gap (clearance).

The turning, rolling and polishing technological parameters shows the Table 1.

TECHNICAL PARAMETERS OF MACHINING OPERATIONS	
Turning	
f (mm/min)	0,133
v_c (m/min)	117
a_p (mm)	1
Rolling	
f (mm/rev)	0,1
v_r (m/min)	22
Polishing	
t (min)	1,5
v_p (m/min)	62

f =feed; v_c cutting speed; a_p = cutting deep; v_r = rolling speed; t = time; v_p = polishing speed

V. EVALUATION

After the manufacturing there are six different surfaces (grinded, turned by simple and Wiper insert). As first step were measured the surfaces roughens by MITUTOYO Formtracer SV-C3000 roughness tester. The measured results see in Table 2.

ROUGHNESS VALUES AFTER MACHINING		
Technology	Ra (μm)	Rz (μm)
Grinded	0,54	3,43
Turned (simple)	1,2	6,09
Rolled	0,40	2,40
Polished	0,96	4,93
Turned (Wiper)	0,45	3,05
Rolled	0,27	1,92
Polished	0,38	2,79

Than was measured the twist surface by thread method. This method is a simple and fast method because it is consist of a thread and weight. The thread made from steel, plastic or wool (e.g.: fishing line or sewing thread). In this research were

used steel thread where the steel diameter of 0,04 mm. The weight depends on the applied thread material and diameter so in this case is 50 g [9].

A. Measuring procedure

During the measurement has to rotate the workpiece in horizontal position and superimpose the thread with the weight (Fig 9.).

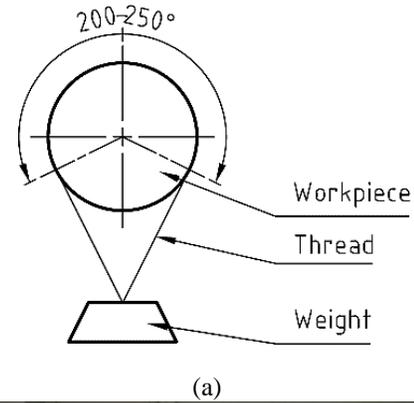
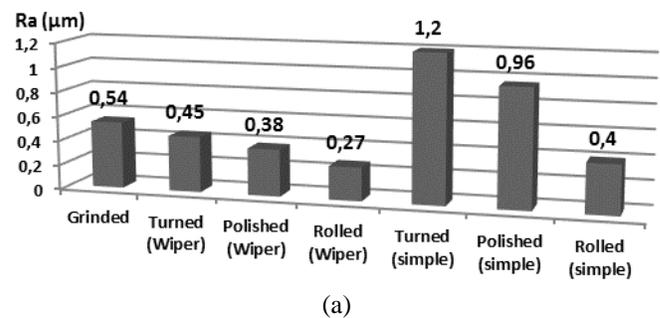
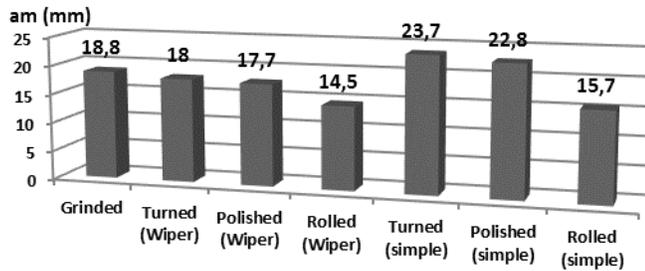


Fig. 9 Thread method a) [9] and during measurement b)

The measuring takes one minute and during this time the workpiece peripheral speed 20 m/min. Then have to measure the displacement of thread (a_1) and must be performed the rotation the other direction and also have to measured it (a_2). The average of two values (3) is the characteristic number of twist surface (a_m) [10]. The results are presented in Fig. 8.

$$a_m = \frac{a_1 + a_2}{2} \quad (\text{mm}) \quad (3)$$





(b)

Fig. 8. Measurement results of Ra roughness a) and characteristic number b) of twist surface

VI. CONCLUSION

The research shows that MAM technologies are new manufacturing opportunity for surfaces to obtain desired functions such as surfaces with tribological function.

According to the expectations the Wiper insert produced a less than twist surfaces compared to the simple one and as you see in the Fig. 8. a) that the grinded surface were worse than the rolled.

According to the Fig. 8. b) instead of grinding can be machined with MAMRB which is faster, economical, easier and some case does not require workpiece transfer. Also there are negatives, like accuracy (size and position) which depends on the previous manufacturing.

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